

CNC-3Axis User Manual

 CAUTION	 CAUTION	 CAUTION
 当心机器伤人 Warning Mechanical Injury	 注意高温 High Temperature	 有电危险 Danger! Electricity

Part B: User manual

Version .1.2

Control board description:

Laser

Spindle

Stepmotor X_Y_Z

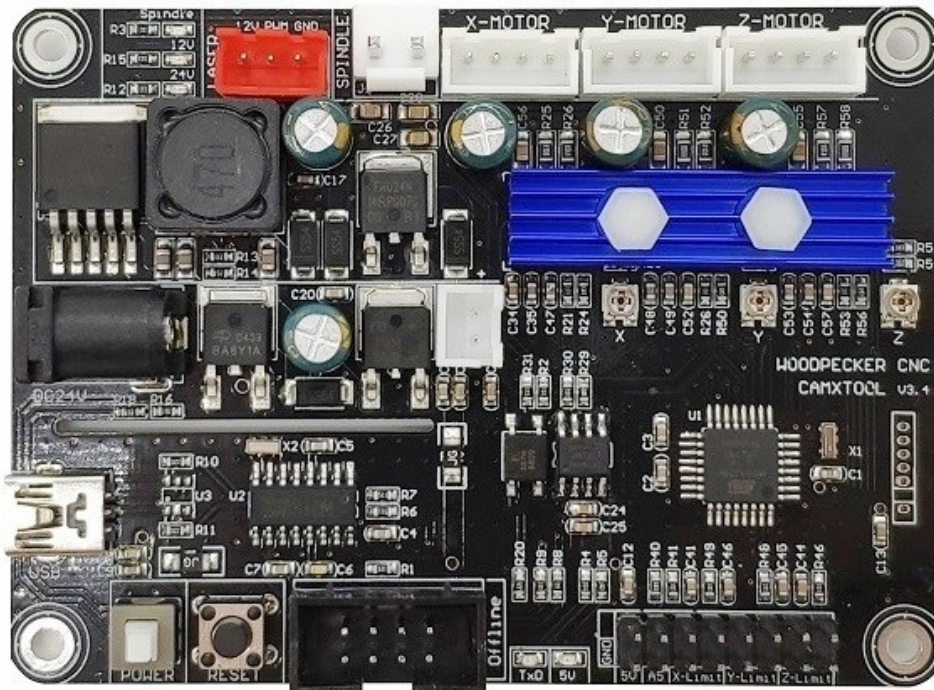


PWM

PWM

DC 24V

USB



Power Button

Reset

Offline Ctrl



Proble

X-limit

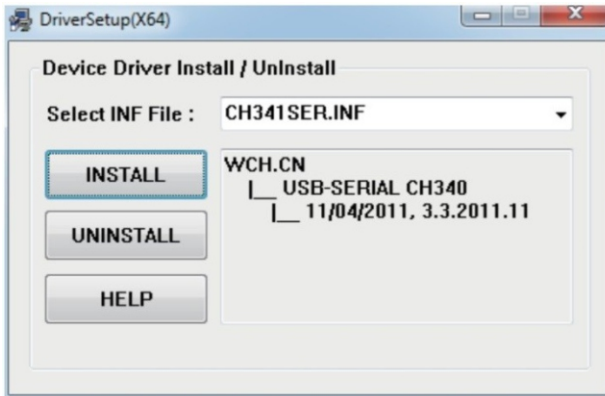
Y-limit

Z-limit



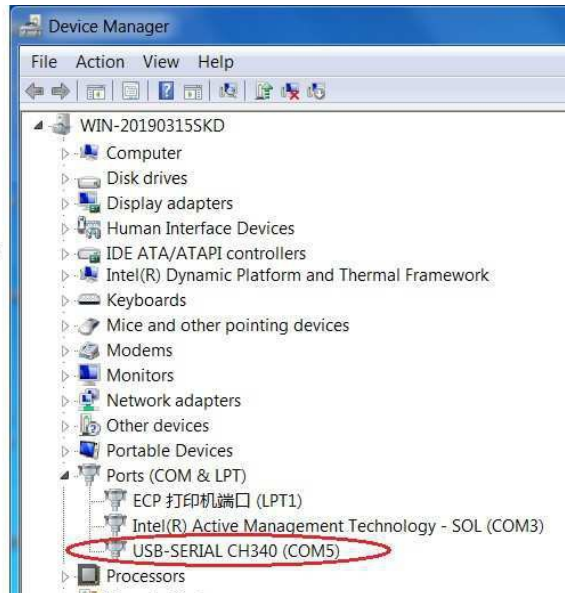
grbl 1.1

Driver install: (software --> Driver --> CH340SER.exe)



Determine your Machine's COM port:

- Windows XP: Right click on "My Computer", select "Properties", select "Device Manager".
- Windows 7: Click "Start" -> Right click "Computer" -> Select "Device Manager" -> "Ports (COM & LPT)"
- Your machine will be the USB Serial Port (COMX), where the "X" represents the COM number, for example COM5.
- If there are multiple USB serial ports, right click each one and check the manufacturer, the machine will be "CH340".



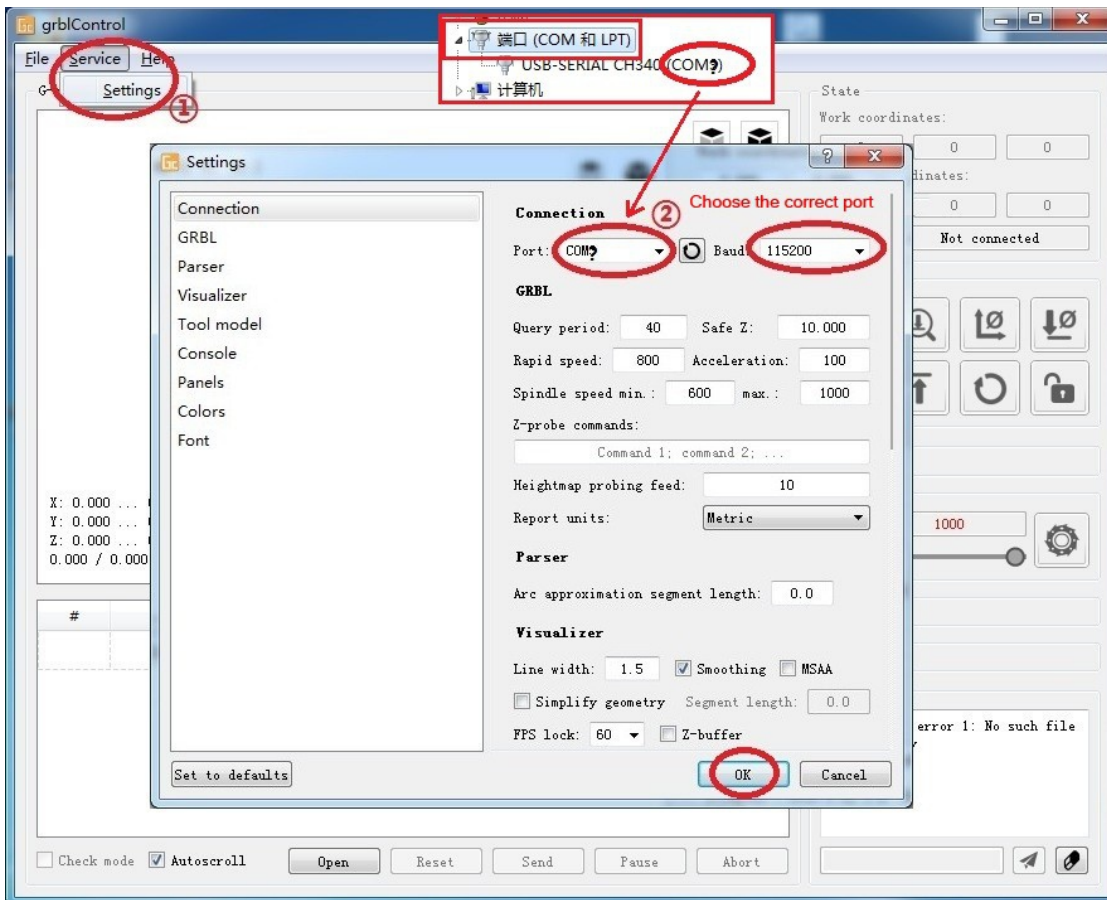
Mode-3Axis-A:(Machining with spindle) & Control with PC

- Use the Usb cable for connecting computers.(Don't plug in the offline controller!)

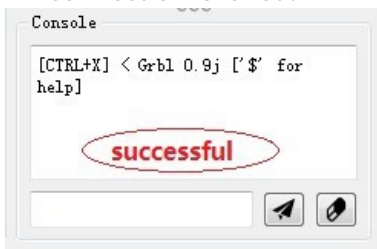
- Open grblControl software(software -> Grblcontrol -> grblControl.exe)

Notice: 1. The 3-Axis NC files need users to design by themselves using CAM software.

2. The grblControl just send the NC file to machine.



- Console window print " [CTRL+X] < Grbl 1.1f ['\$' for help]" If the connection is successful.
- Console window print " Serial port error 1: No such file or directory " indicate that the connection is failed.



Grblcontrol Use

The screenshot shows the grblControl software interface. The main window displays a G-code program: `[G0 G54 G17 G21 G90 G94 M0 M5 M9 T0 F0. S0.]`. A red box highlights the spindle speed control area, which includes a slider and a gear icon. The slider is set to 1000. Annotations explain that the spindle speed is a ratio, not the actual speed, and that the percentage is not linear. A text box provides the following calculations: $100 = 100/1000 \rightarrow 10\%$ and $1000 = 1000/1000 \rightarrow 100\% \text{ max}$. Another text box states: "And this percentage is not linear." The right sidebar shows the state of the machine, including work and machine coordinates, and a control panel with buttons for home, stop, and jog. The jog panel is also highlighted with a red box and labeled "The X Y Z axis jog". The jog panel includes a "Step:" field set to 1.00 and four directional buttons. The bottom of the interface features a console area with a table for commands and responses, and a row of buttons: Open, Reset, Send, Pause, and Abort. Red arrows point from the annotations to the "Open" button and the "Send" button, with labels "Open the G-code file" and "start working!".

The spindle speed :

!!! It does not represent the actual speed, and it represents the ratio. And this percentage is not linear.

100 = 100/1000 -> 10%
1000 = 1000/1000 -> 100% max

And this percentage is not linear.

spindle on/off

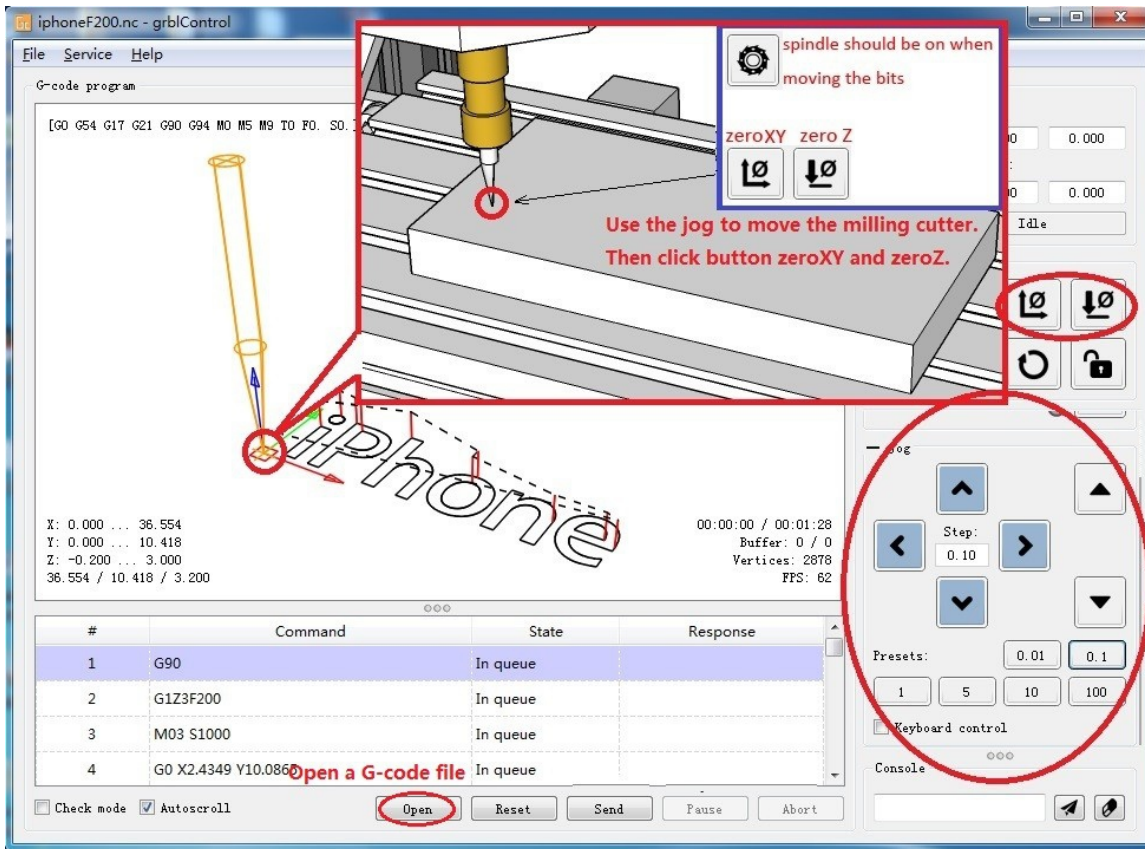
The X Y Z axis jog

Open the G-code file start working !

#	Command	State	Response

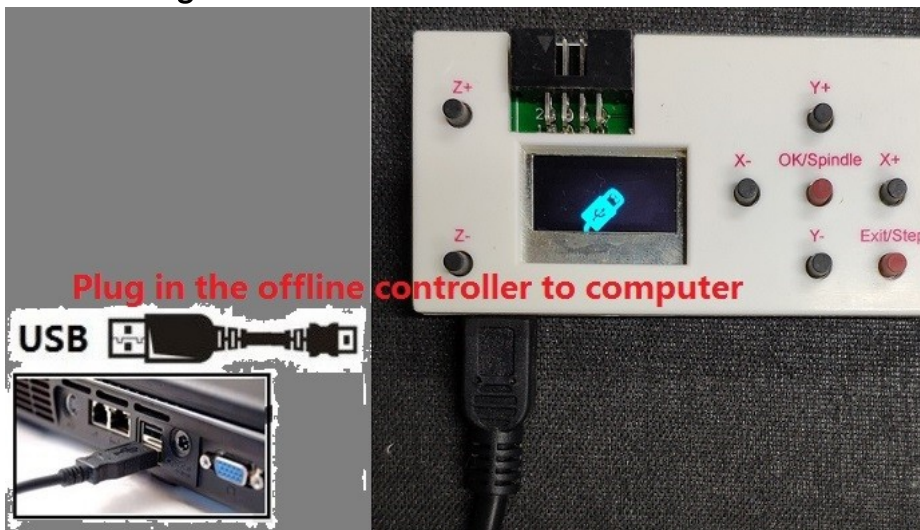
Check mode Autoscroll Open Reset Send Pause Abort

Tool setting



Mode-3Axis-B:(Machining with spindle) & Control with Offline Controller

- Connecting the Offline Controller to PC with the USB cable.



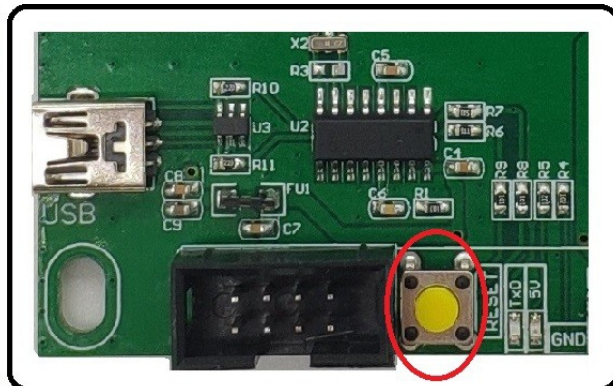
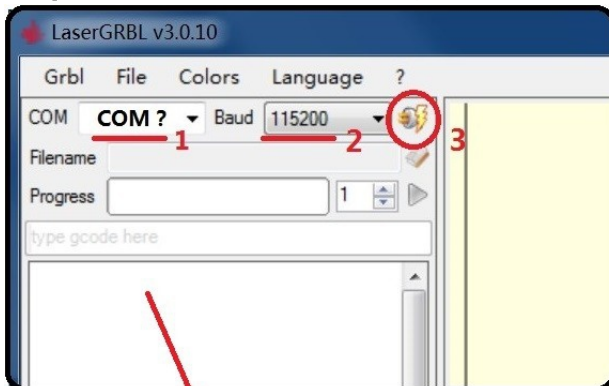
- Then. Save the "3-Axis NC" file to Offline Controller.

- Refer to the "Offline Controller User Manual" to work begin.

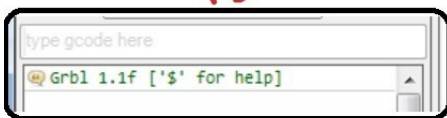
Notice: The 3-Axis NC files need users to design by themselves using CAM software.

Mode-2Axis-A:(Machining with Laser) & Control with PC

- Use the Usb cable for connecting computers.(Don't plug in the offline controller!)
- Open LaserGRBL software(laser -> laserGRBL) and install.

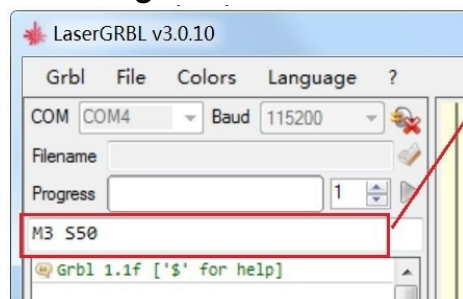


4. then press the button



- Console window print " Grbl 1.1f ['\$' for help]"
If the connection is successful.
- If the port selection is wrong, no information will be returned.

- Focusing



Input "M3 S50" .then press Enter.

(Or create a custom button if you want to be easy.
Refer to "CUSTOM BUTTOM")

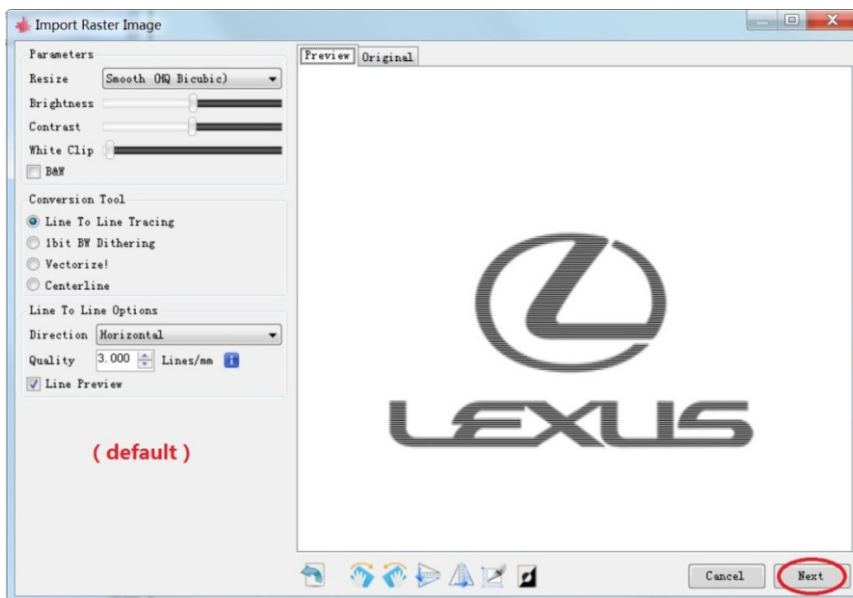
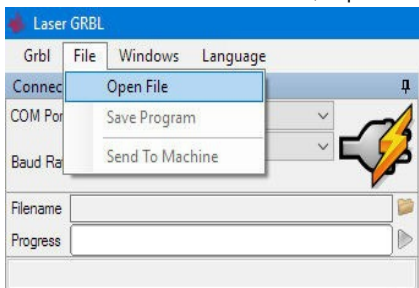
The laser will be turned on with low power model. Then Rotate the lens to minimize the spot.

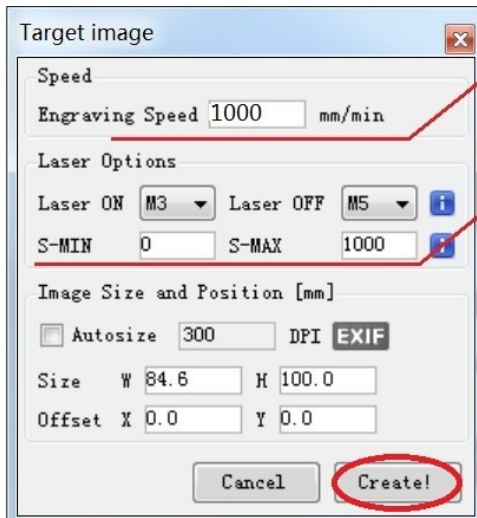


- RASTER IMAGE IMPORT

Raster import allows you to load an image of any kind in LaserGRBL and turn it GCode instructions without the need of other software. LaserGRBL supports photos, clip art, pencil drawings, logos, icons and try to do the best with any kind of image.

It can be recalled from "File, Open File" menu by selecting an image of type jpg, png or bmp.



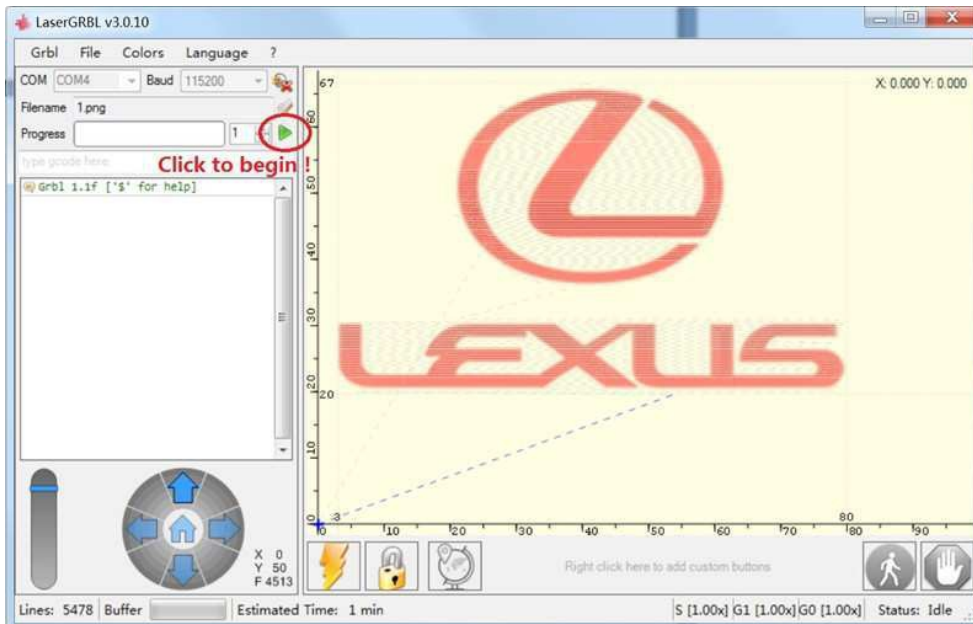


Reference speed : 1000

Power to laser
(Duty cycle of the PWM)

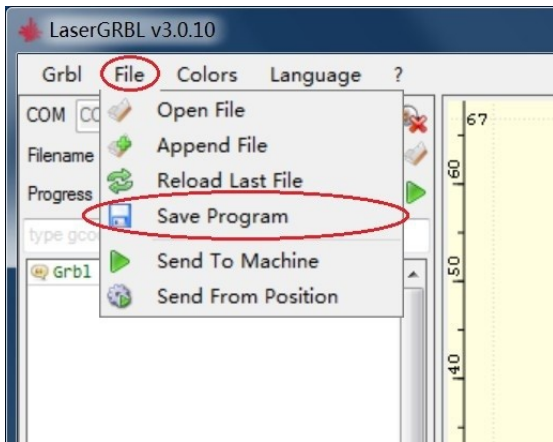
Notice: speed and S value are different with material.

- Click this button to begin **if use the computer control.**



- Save program to "NC" file **if use the offline controller.**

(Mode-2Axis-B: (Machining with Laser) & Control with Offline Controller)



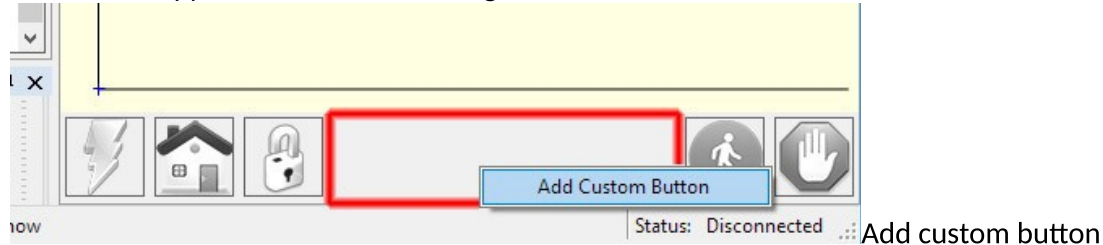
- Offline controller can be used as card reader through USB cable.
- Then Plug in the offline controller to control board. (Don't plug in the USB cable to computer)
- Then. Refer to the "Offline Controller User Manual" to work begin.

EXPERT MODE

- Expert mode lets users have more control over the machine. But Users should have some professional knowledge

1. Custom button in the laserGRBL software.

LaserGRBL support custom buttons. Right-click in button area to add a new custom button.

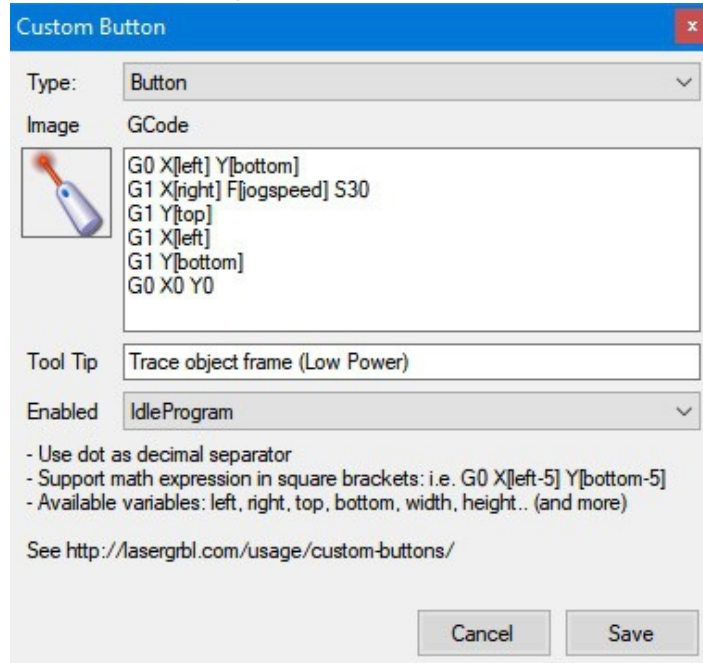


In custom button you can write a set of G-Code instruction to execute customized actions.

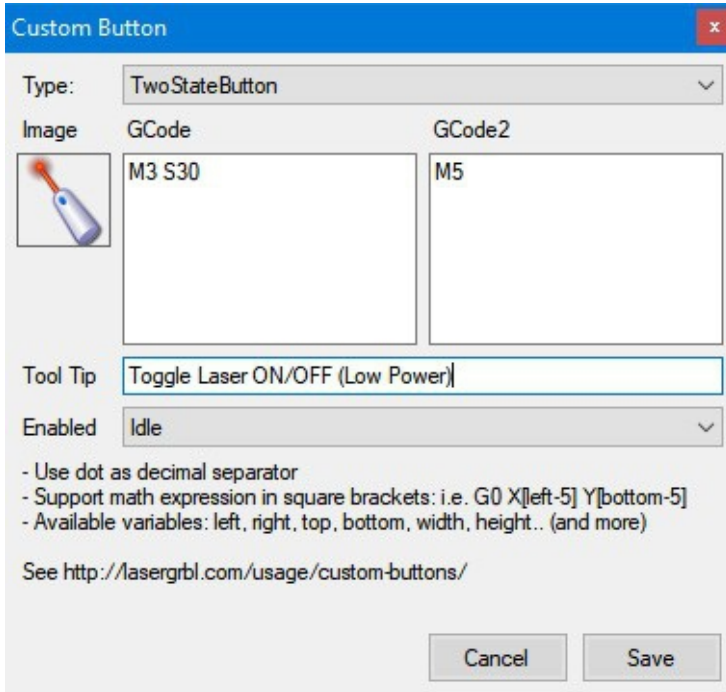
There is 3 types of custom buttons:

- Button
- TwoStateButton
- PushButton

Custom button of type “Button” contains a block of GCode to be executed on click. This could be used to launch a series of gcode instruction i.e. for trace a frame around an image or set a new zero position.



“TwoStateButton” contains two block of GCode. The first action is executed on a first click, then the second action is executed on a second click. This is very useful for action like toggling laser on-off to see its position



Toggle laser ON/OFF

“PushButton” is similar to “TwoStateButton” but the first action is executed on mouse down, the second is executed on mouse up.

Custom Buttons support a series of variables that can be used in expressions. Here is the full set of supported variables:

left	Left margin of loaded image (X)
right	Right margin of loaded image (X)
top	Top margin of loaded image (Y)
bottom	Bottom margin of loaded image (Y)
width	Width of loaded image
height	Height of loaded image
jogstep	Actual value of jog step cursor
jogspeed	Actual value of jog speed cursor
WCO.X	Actual value of WCO X (Work Coordinate Offset) use .X.Y.Z
MPos.X	Actual Machine position. Support .X.Y.Z
WPos.X	Actual Work position. Support .X.Y.Z

2. Default configuration

Grbl \$\$ configuration					
#	Parameter	Value	Unit	Description	
\$0	Step pulse time	10	microseconds	Sets time length per step. Minimum 3usec.	
\$1	Step idle delay	25	milliseconds	Sets a short hold delay when stopping to let dynamics settle...	
\$2	Step pulse invert	0	mask	Inverts the step signal. Set axis bit to invert (00000ZYX).	
\$3	Step direction invert	5	mask	Inverts the direction signal. Set axis bit to invert (00000Z...	
\$4	Invert step enable pin	0	boolean	Inverts the stepper driver enable pin signal.	
\$5	Invert limit pins	0	boolean	Inverts the all of the limit input pins.	
\$6	Invert probe pin	0	boolean	Inverts the probe input pin signal.	
\$10	Status report options	1	mask	Alters data included in status reports.	
\$11	Junction deviation	0.010	millimeters	Sets how fast Grbl travels through consecutive motions. Lowe...	
\$12	Arc tolerance	0.002	millimeters	Sets the G2 and G3 arc tracing accuracy based on radial erro...	
\$13	Report in inches	0	boolean	Enables inch units when returning any position and rate valu...	
\$20	Soft limits enable	0	boolean	Enables soft limits checks within machine travel and sets al...	
\$21	Hard limits enable	0	boolean	Enables hard limits. Immediately halts motion and throws an ...	
\$22	Homing cycle enable	0	boolean	Enables homing cycle. Requires limit switches on all axes.	
\$23	Homing direction invert	0	mask	Homing searches for a switch in the positive direction. Set ...	
\$24	Homing locate feed rate	25.000	mm/min	Feed rate to slowly engage limit switch to determine its loc...	
\$25	Homing search seek rate	500.000	mm/min	Seek rate to quickly find the limit switch before the slower...	
\$26	Homing switch debounce delay	250	milliseconds	Sets a short delay between phases of homing cycle to let a s...	
\$27	Homing switch pull-off distance	1.000	millimeters	Retract distance after triggering switch to disengage it. Ho...	
\$30	Maximum spindle speed	1000	RPM	Maximum spindle speed. Sets PWM to 100% duty cycle.	
\$31	Minimum spindle speed	0	RPM	Minimum spindle speed. Sets PWM to 0.4% or lowest duty cycle.	
\$32	Laser-mode enable	0	boolean	Enables laser mode. Consecutive G1/2/3 commands will not hal...	
\$100	X-axis travel resolution	1600.000	step/mm	X-axis travel resolution in steps per millimeter.	
\$101	Y-axis travel resolution	1600.000	step/mm	Y-axis travel resolution in steps per millimeter.	
\$102	Z-axis travel resolution	1600.000	step/mm	Z-axis travel resolution in steps per millimeter.	
\$110	X-axis maximum rate	1000.000	mm/min	X-axis maximum rate. Used as G0 rapid rate.	
\$111	Y-axis maximum rate	1000.000	mm/min	Y-axis maximum rate. Used as G0 rapid rate.	
\$112	Z-axis maximum rate	800.000	mm/min	Z-axis maximum rate. Used as G0 rapid rate.	
\$120	X-axis acceleration	30.000	mm/sec ²	X-axis acceleration. Used for motion planning to not exceed ...	
\$121	Y-axis acceleration	30.000	mm/sec ²	Y-axis acceleration. Used for motion planning to not exceed ...	
\$122	Z-axis acceleration	30.000	mm/sec ²	Z-axis acceleration. Used for motion planning to not exceed ...	
\$130	X-axis maximum travel	200.000	millimeters	Maximum X-axis travel distance from homing switch. Determine...	
\$131	Y-axis maximum travel	200.000	millimeters	Maximum Y-axis travel distance from homing switch. Determine...	
\$132	Z-axis maximum travel	200.000	millimeters	Maximum Z-axis travel distance from homing switch. Determine...	